



GMES and European Earth Observation Missions

DLR – Conabio Workshop:
Use of remote sensing data for environmental and civil security applications in Mexico

Gunter Schreier
Head Business Development
DLR-DFD, Oberpfaffenhofen, Germany
Mexico City, April 22nd to 24th, 2008



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GMES: Global Monitoring of Environment and Security



- ↗ The next EU flagship for Space after Galileo (2nd Space Council, June 2005)
- ↗ An EU-led initiative, in which the Commission will manage actions for identifying and developing **services** relying both on in-situ and remote sensing data and ESA will implement the **space component**. **National missions** are part of the space component.
- ↗ GMES is European contribution to **GEO/GEOSS**
- ↗ Implementation thru:
 - ↗ ESA GMES space component (incl. ground segment interfaces)
 - ↗ EU FP7 Space budget (R&D budget)
 - ↗ Dedicated direct actions (European and national)
 - ↗ Guideline: Munich Roadmap



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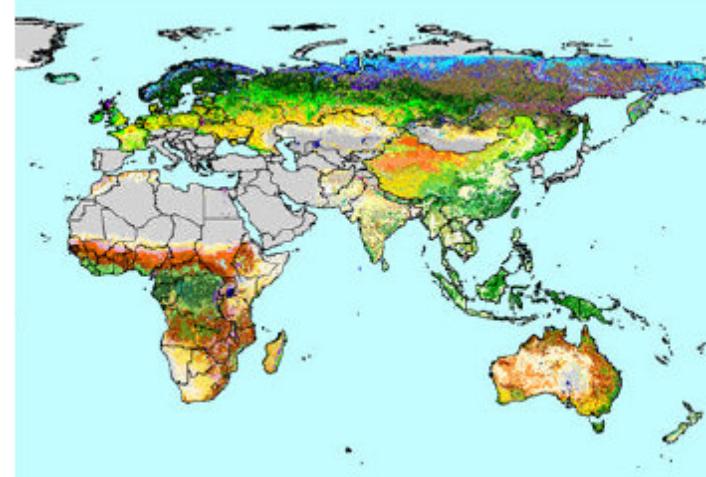
Environment and Security

Environment

Protecting the planet by

better measurements of environmental stress,
biodiversity, desertification, carbon fluxes,
pollution, urbanisation, eutrophication....

- slow-change, coarse resolution data



Security

Protecting the individual by

Monitoring threats and vulnerabilities
Providing early warnings (increase preparedness)
Supporting operations

- rapid change, high resolution data



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GMES: Global Monitoring of Environment and Security

Space Systems

Observational Networks

Data Centers

Three
Core Services



Plus Two Pilot
Services

Downstream Services, t.b.d.

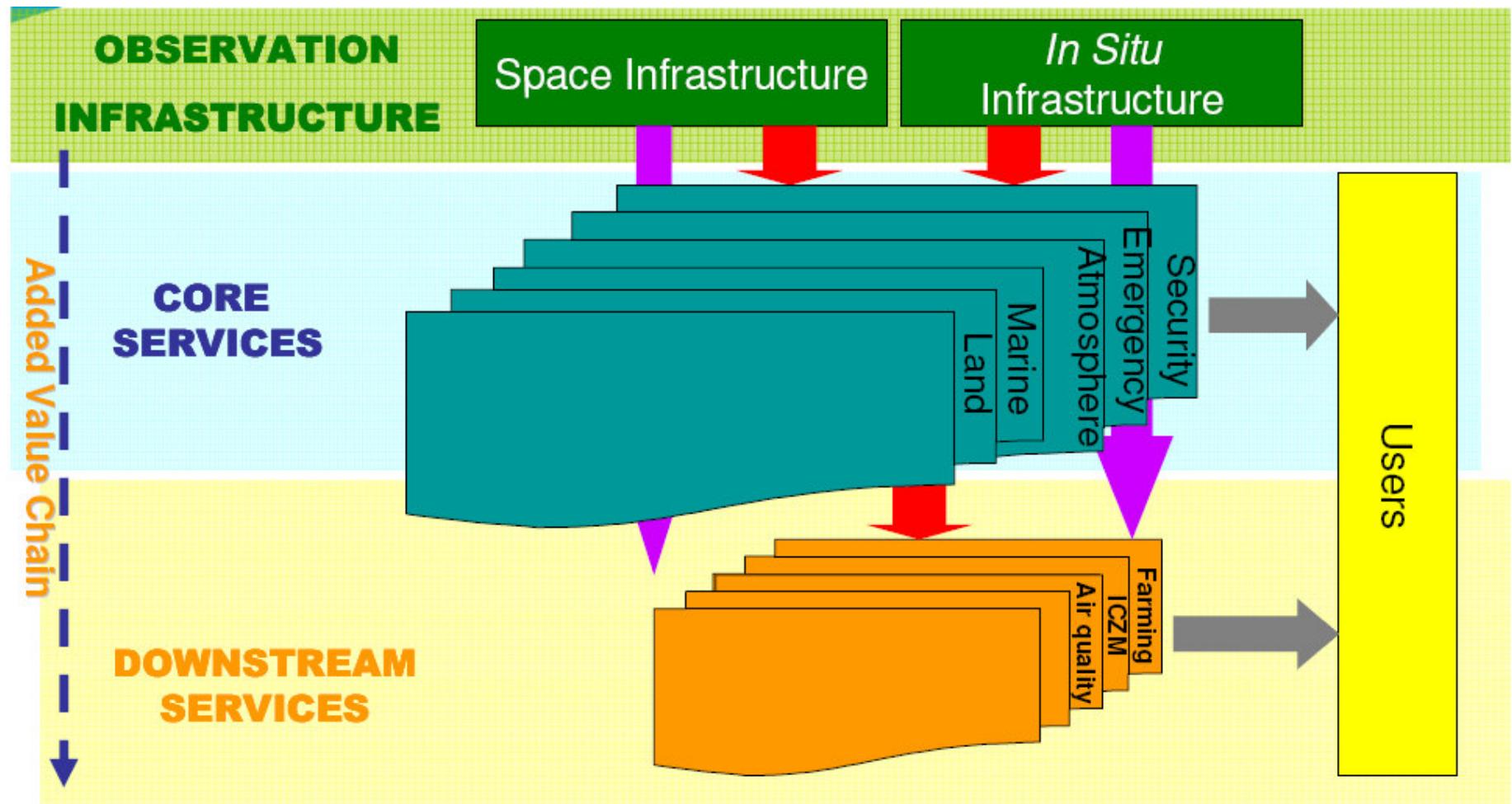


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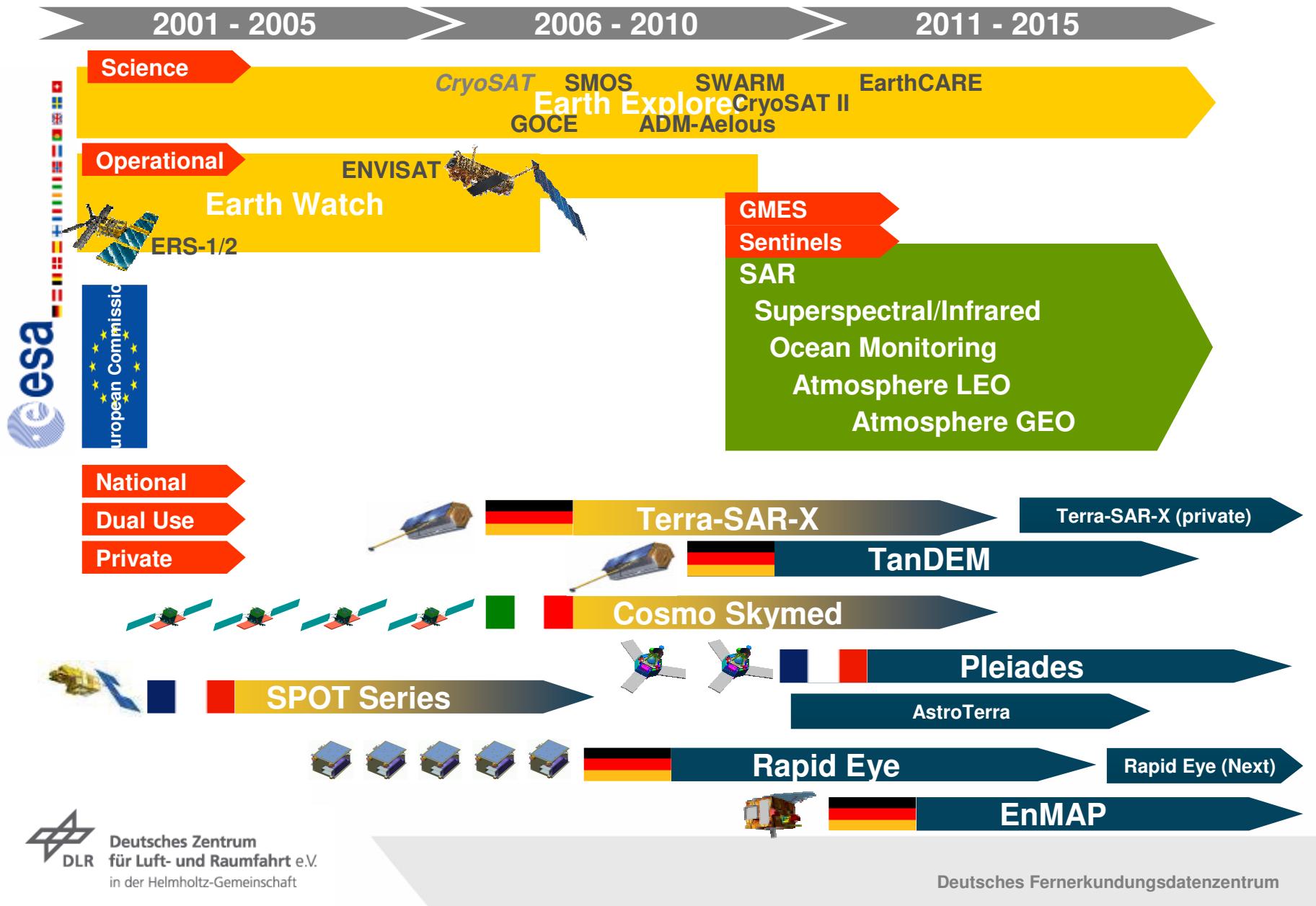


GMES: Global Monitoring of Environment and Security





The European Fleet of GMES Satellites





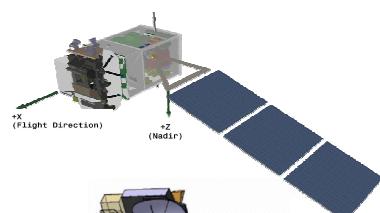
GMES dedicated missions: Sentinels



Sentinel 1 – SAR imaging

2011

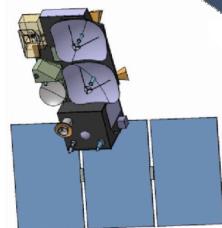
All weather, day/night applications, interferometry



Sentinel 2 – Multispectral imaging

2012

Land applications: urban, forest, agriculture, etc Continuity of Landsat, SPOT data



Sentinel 3 – Ocean and global land monitoring

2012

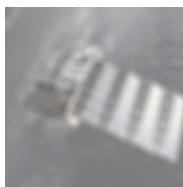
Wide-swath ocean color, vegetation, sea/land surface temperature, altimetry



Sentinel 4 – Geostationary atmospheric

2017+

Atmospheric composition monitoring, trans-boundary pollution



Sentinel 5 – Low-orbit atmospheric

2019+

Atmospheric composition monitoring



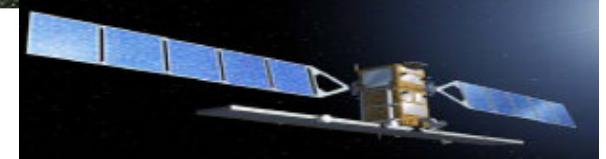
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From ESA presentation April 10th, 2008

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ESA SENTINEL - 1



Main Objectives

Provide continuity of C-band radar observations & Satisfy the GMES service requirements in terms of data availability, coverage & revisit, timeliness and the quality of its data products by:

- an operational concept based mostly on the use of a pre-defined acquisition scenario
- a systematic processing
- the NRT on-line delivery of data products

Main Characteristics

Orbit: Near Polar Sun-Synchronous

Repeat cycle: 12 days. 175 orbits

Payload: C-Band Synthetic Aperture Radar

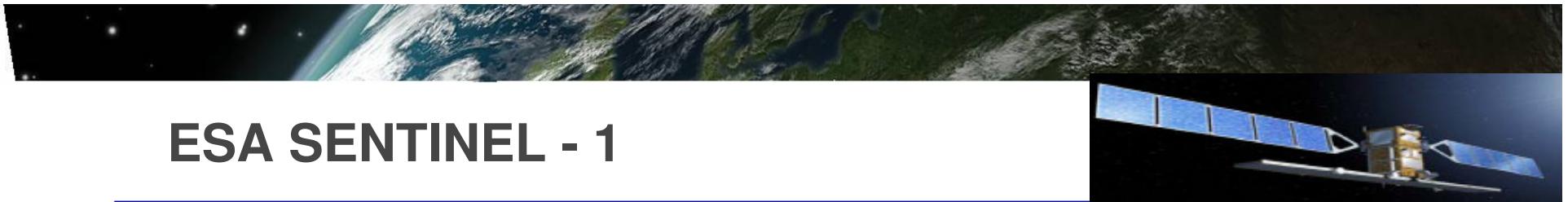
Constellation: Sentinel-1 system will be composed of two satellites, Sentinel-1 A & B, to be launched 2 years apart

Schedule

Launch: Q4 2011 (Sentinel-1A)

Parameter	Value
Centre Frequency	5.406 GHz
Bandwidth	0 ± 100 MHz (programmable)
Polarization	HHVW, VV-VH
Pulse Width	5-100 µs (programmable)
Transit Duty cycle	12% max
Pulse Repetition Frequency	1000 ± 3000 Hz (programmable)
Data Compression	Selectable, according to BC - BAD
Instrument mass	927 kg
DC Power consumption	< 3700 W
Antenna Size	12.3 m x 1.02 m
Number of tiles	14
Number of T/R modules per tile	20
RF Peak Power	~ 4.2 kW





ESA SENTINEL - 1

- **Interferometric Wide Swath Mode**

ScanSAR based with progressive azimuth scanning, dual polarization, large swath, high spatial resolution, burst synchronisation for ScanSAR interferometry

- **Extra Wide Swath Mode**

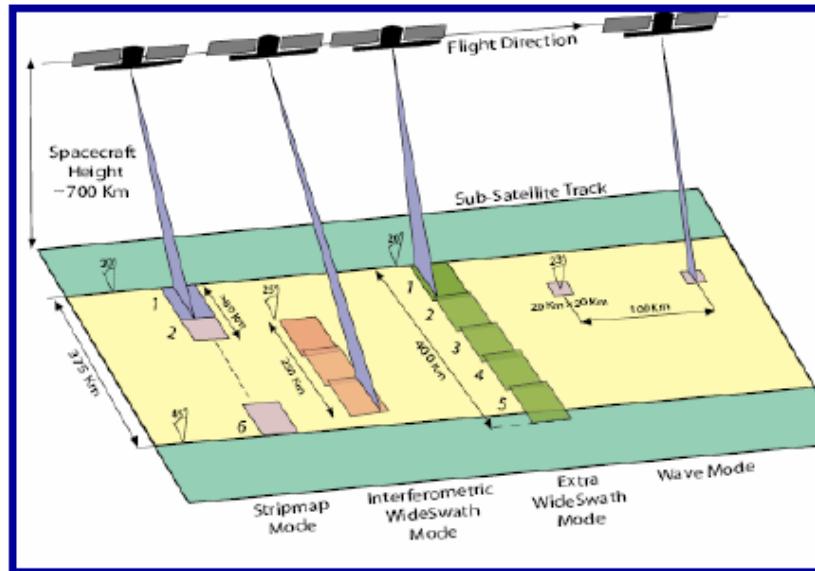
ScanSAR based, dual polarization, very large swath, reduced spatial resolution.

- **StripMap Mode**

Dual polarization, medium swath, high radiometric performance, very high spatial resolution

- **Wave Mode**

Sampled StripMap mode, single polarization, low data rate.



Mode	Polarization	Swath Width	Resolutions
StripMap	HH-HV, VV-VH	> 80 Km	5m (range) x 5m (azim)
Interferometric Wideswath	HH-HV, VV-VH	250 Km	5m (range) x 20m (azim)
Extrawide Swath	HH-HV, VV-VH	400 Km	25m (range) x 100m (azim)
Wave Mode	HH, VV	20 Km x 20 Km (Vignette)	20m (range) x 5m (azim)

**Duty cycle per orbit
(sizing requirements):**

- 5 min in Stripmap mode
- 15 min in IWS mode
- 40 min in WV mode



ESA SENTINEL - 2



Main Objectives

- To provide continuity of Landsat and SPOT, by making continuous observations on all land surfaces
- To establish a European source of data fulfilling the requirements of the GMES services (Land Use, Forest, Emergency)

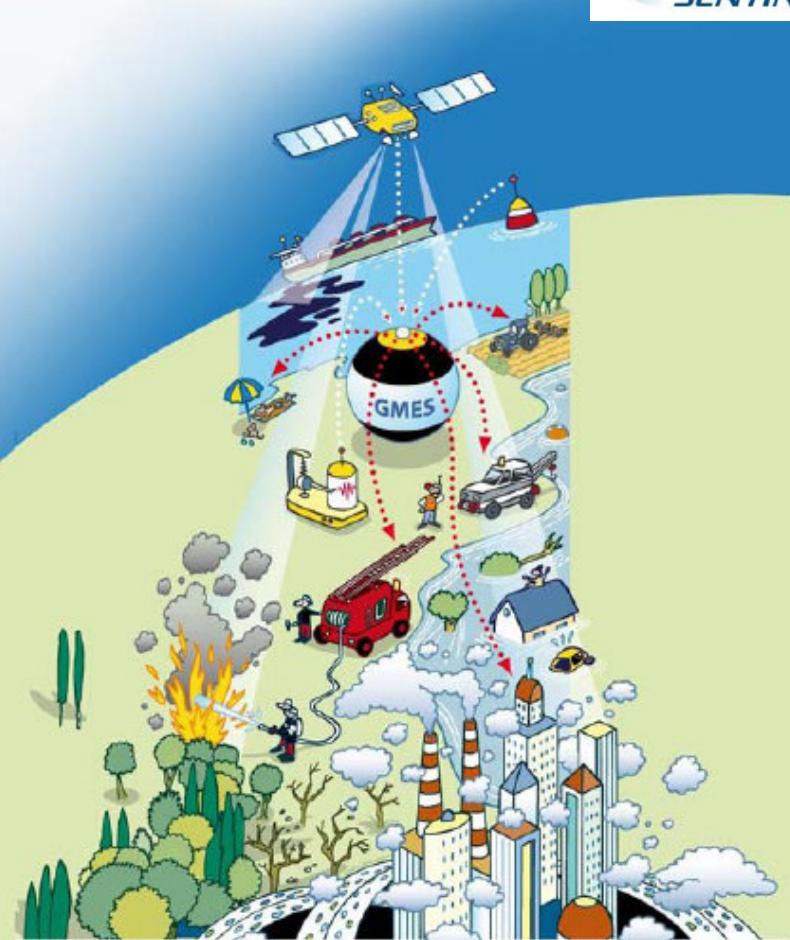
Orbit: Near Polar Sun-Synchronous

Repeat cycle: 10 days. 143 orbits

Payload: Multi-spectral Instrument (MSI)

Constellation: Sentinel-2 system will be composed of two satellites, Sentinel-2A&B, to be launched ~2 years apart

Coverage: Systematic imaging of all land surfaces between 83 N and 53 S with SZA better than 75 deg.

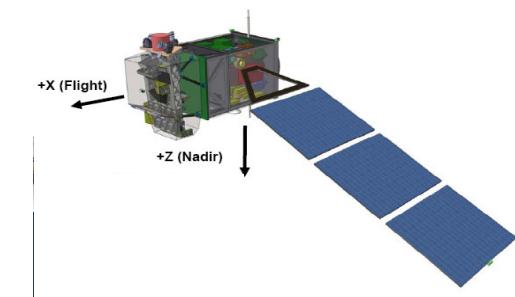


Launch: Q4 2012



ESA SENTINEL - 2

- **MSI (Multi-Spectral Imager)**
 - Swath: 285 Km
 - 13 Bands @ 10-60 m resolution, from VNIR to SWIR
 - Radiometric Resolution 12 bit
 - Onboard calibration
 - Push-broom technology
- **Accurate geo-location**
 - Standard product: orthorectified corrected image (including atmosphere)
 - <20m 2sigma achievable automatically using AOCS



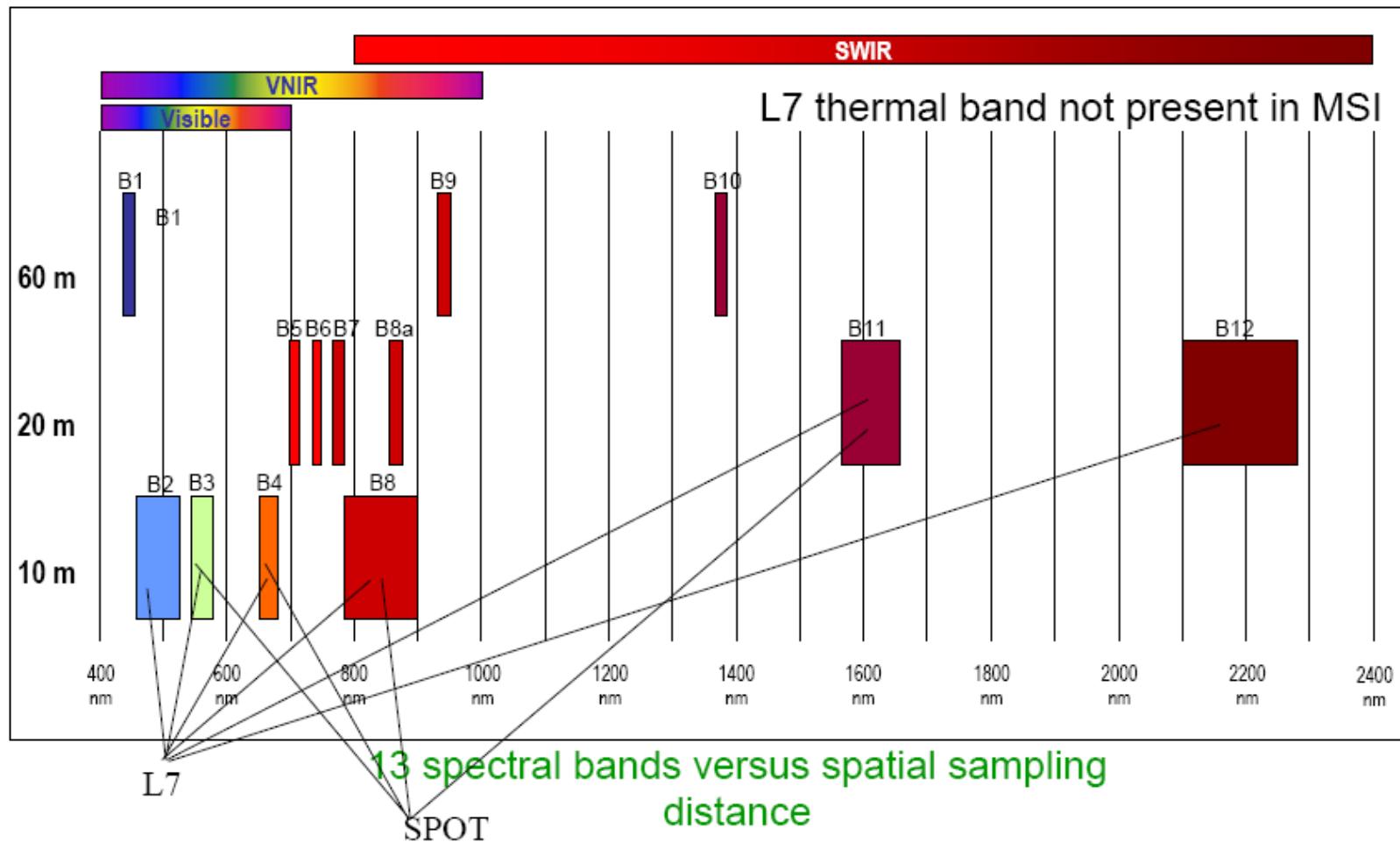
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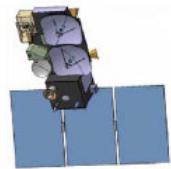
ESA SENTINEL - 2



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ESA SENTINEL - 3

Main Objectives

Provide continuity of medium resolution sensors by ensuring the provision of:

- Ocean observations data (i.e. Sea-Surface Height, Sea-Surface Temperature, Ocean Colour)
- Land optical observation products (i.e. Land Colour, Land Surface Temperature)
- Ice topography products (i.e. Sea Ice, Ice sheet interiors, ice sheet margins)
- Land hydrology products (i.e. water surface levels for river and lakes)

Main Characteristics

Orbit: Near Polar frozen Sun-Synchronous

Repeat cycle: 27 days. 385 orbits

Payload: An Ocean and Land Colour Instrument (OLCI)

A Sea and Land Surface Temperature (SLST) Instrument

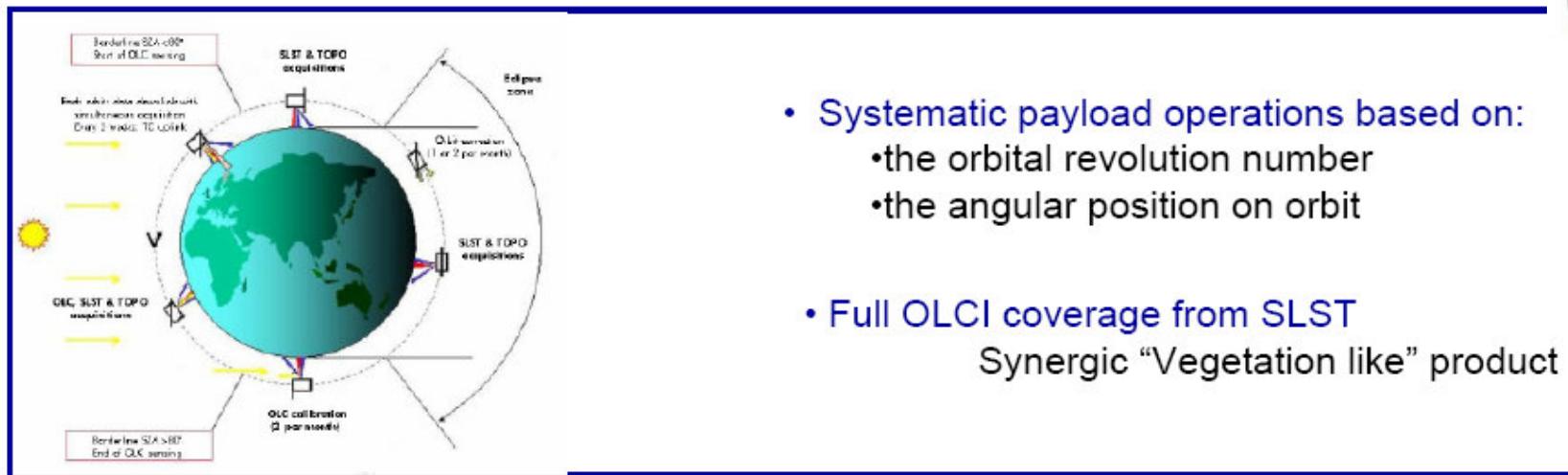
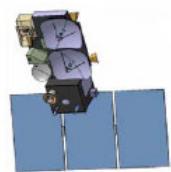
A Radar Altimeter (SRAL)

Schedule

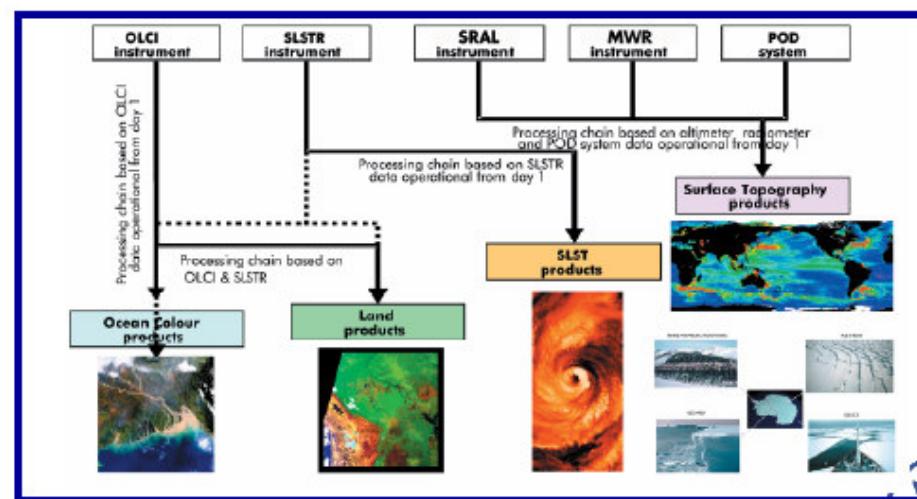
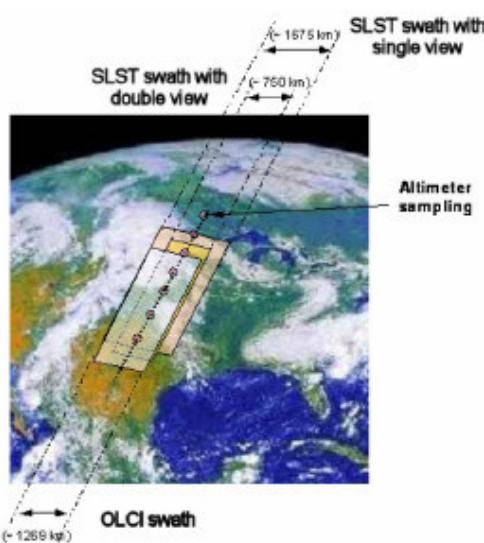
Launch: Q4 2012 (Sentinel-3A)



ESA SENTINEL - 3



- Systematic payload operations based on:
 - the orbital revolution number
 - the angular position on orbit
- Full OLCI coverage from SLST
Synergic “Vegetation like” product



* Illustrations are courtesy from S3 Industrial project team



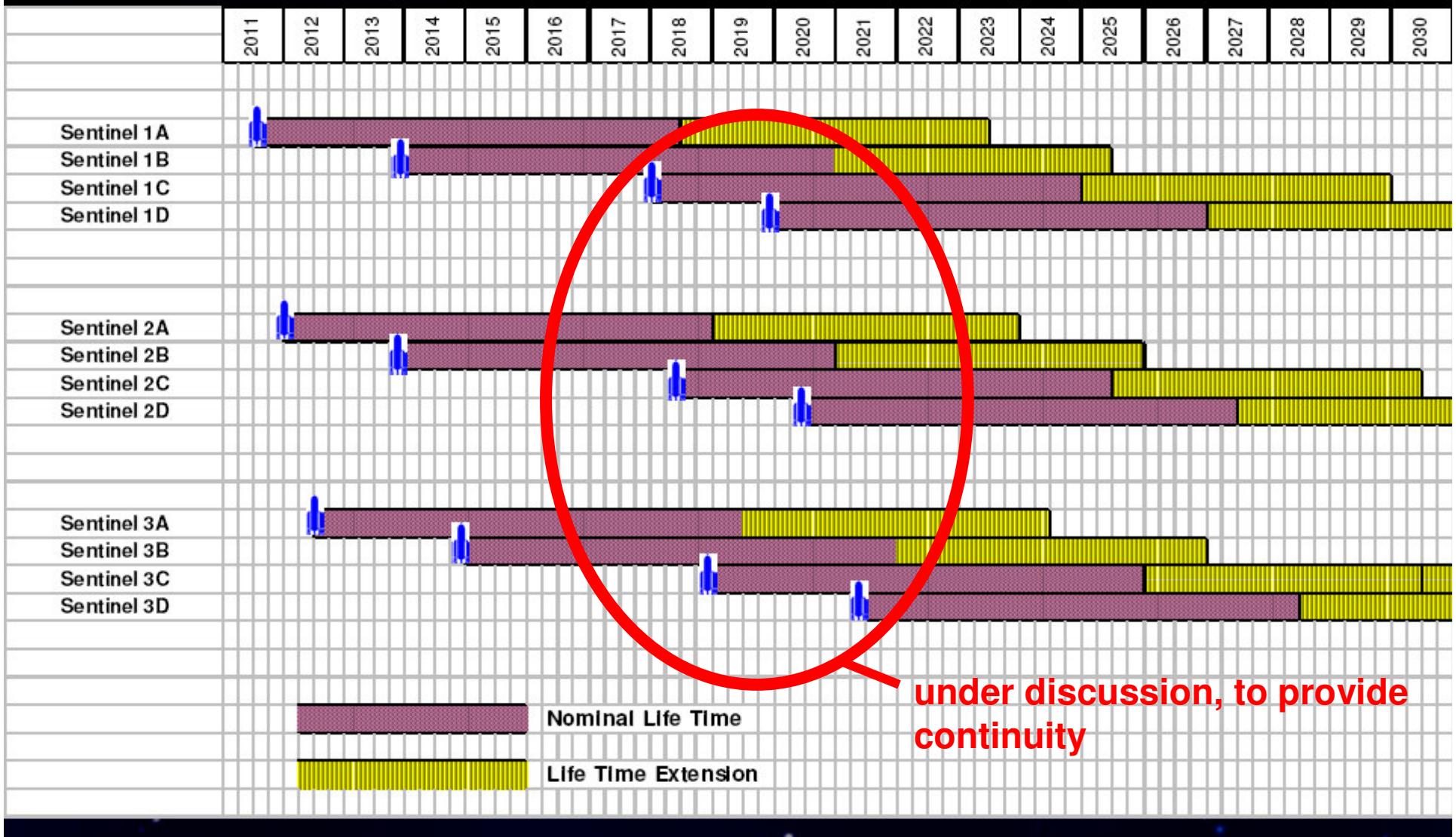
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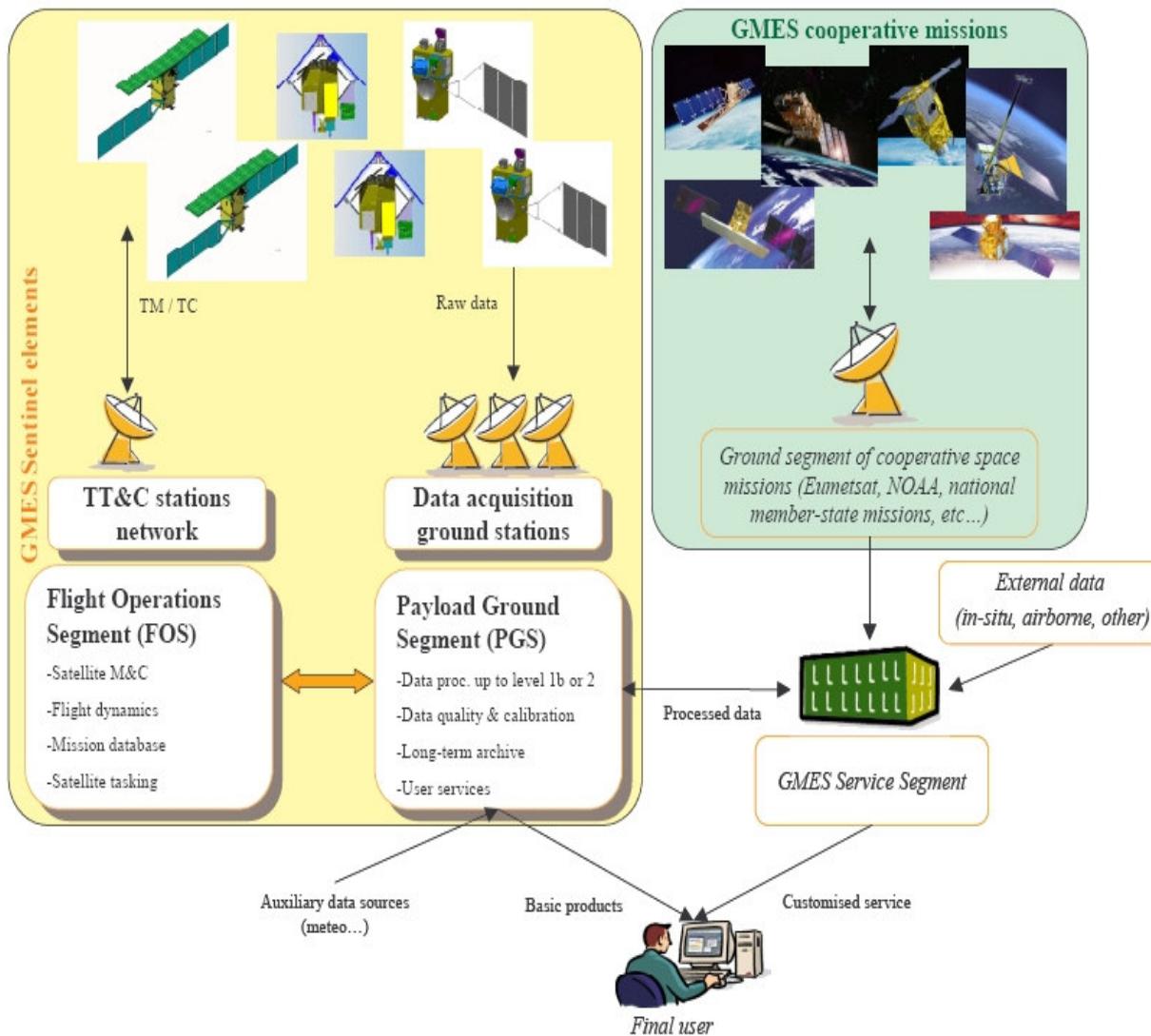


Possible long-term scenario (Sentinels-1/-2/-3 only)





GMES Ground Segment and Data Access



GMES Ground Segment is composed of

→ **FOS**

to operate spacecraft platform and payload

→ **PDGS**

to distribute EO data and products to user communities

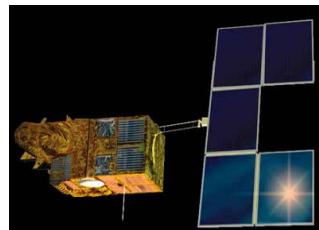


Contributions to GMES Space Component

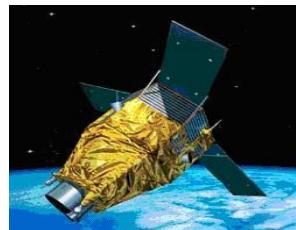
National, Eumetsat and Third Party Missions for GMES
(list non exhaustive)



CosmoSkymed



SPOT



Pléiades



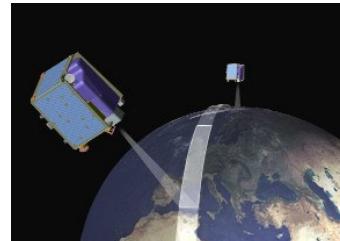
Jason



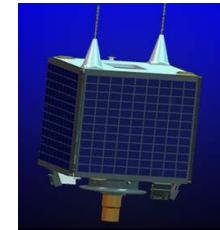
Radarsat



Terrasar-X



RapidEye



DMCs



METOP



MSG

+ Seosat, TanDEM-X, EnMap, Venus, Altika, etc.



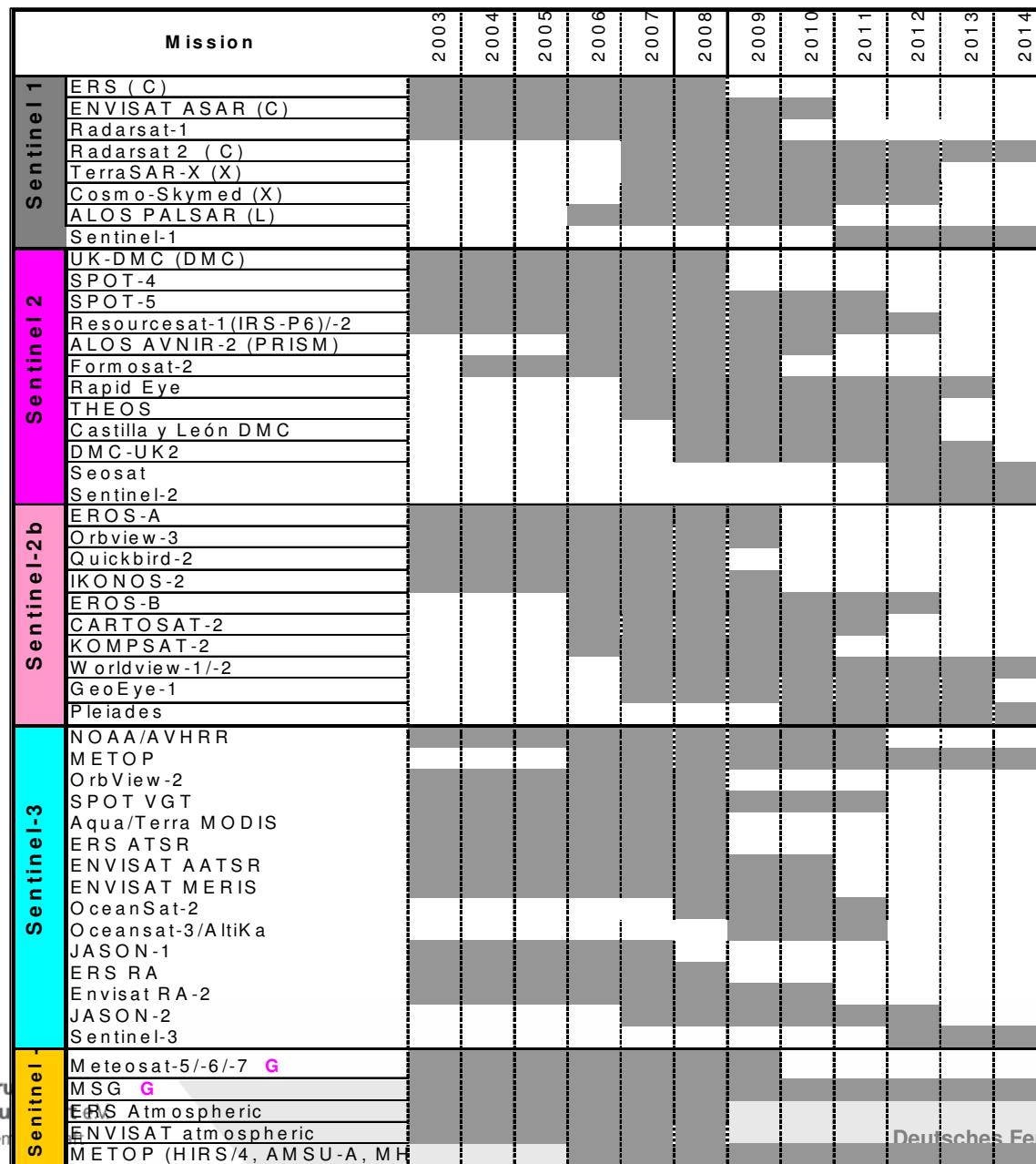
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The extended fleet of GMES Satellites





Cosmo SkyMed

↗ Owner

- ↗ ASI
- ↗ Military and commercial use

↗ Constellation

- ↗ 4 active satellites in 2 orbital planes

↗ Launch date

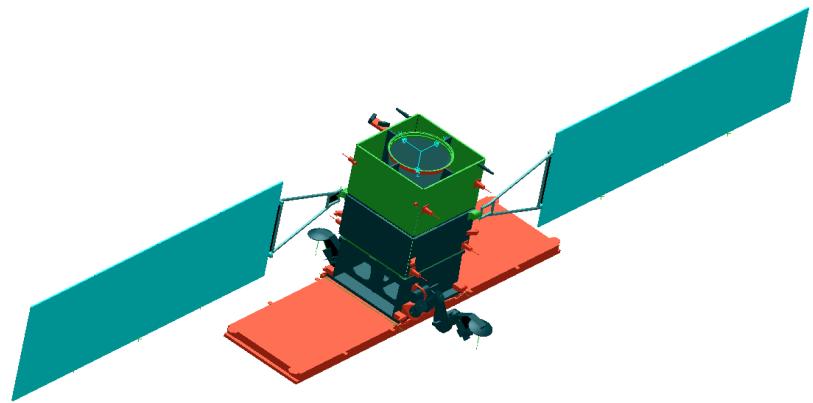
- ↗ June 7th, 2007 (1st sat)

↗ Prime Instrument

- ↗ X-Band SAR, single and dual polarizations

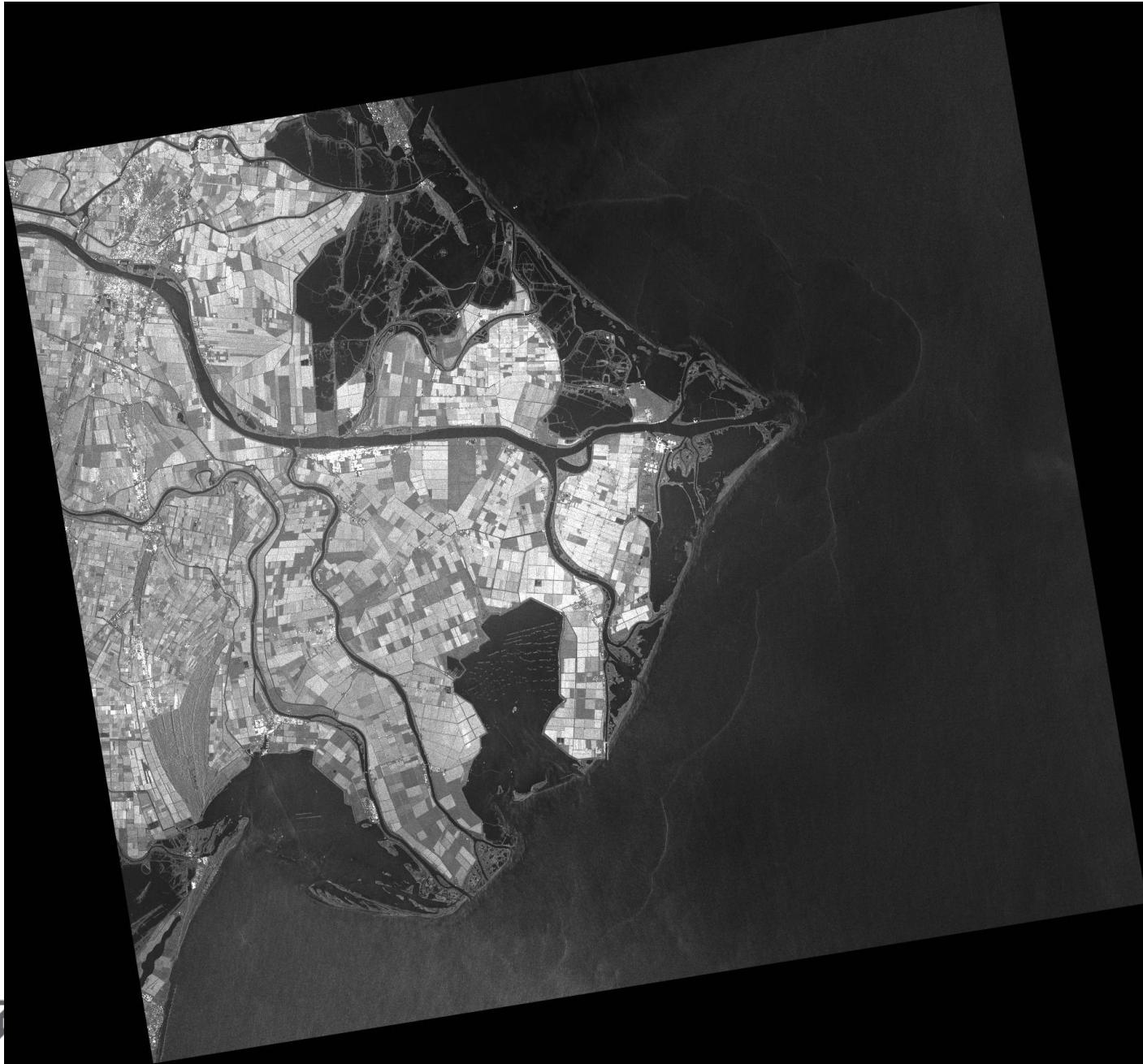
↗ Resolution/swath

- ↗ Spotlight better than 1 m
- ↗ HIMAGE 5m /40 km
- ↗ WIDEREIGION 30 m / 100 km
- ↗ HUGEREGION 100 m / 200 km
- ↗ PINGPONG (dual pol) 15m/ 30 km



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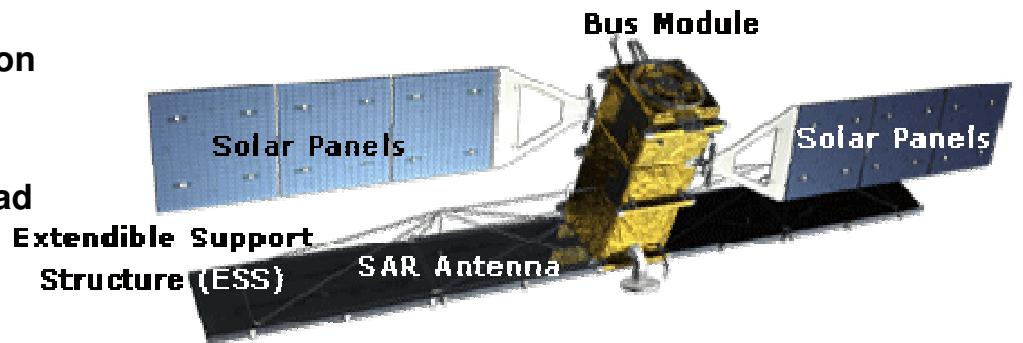
Po-Delta
Cosmo-Skymed
5 m res.



Radarsat-2

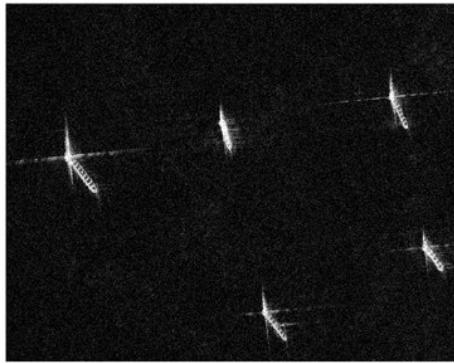


- ↗ Owner
 - ↗ MacDonald Dettwiler Corporation, Canada
- ↗ Launch date
 - ↗ December 14th, 2007
- ↗ Orbit
 - ↗ 789 km @ 98,5 deg inclination
- ↗ Prime Instrument
 - ↗ C-Band SAR, single and quad polarizations
- ↗ Resolution/swath
 - ↗ Ultrafine: 3 m
 - ↗ Multi-Look Fine: 8m
 - ↗ Standard: 25m
 - ↗ Standard Quad Pol: 15m
 - ↗ ScanSAR Narrow: 50m
 - ↗ ScanSAR Wide: 100m



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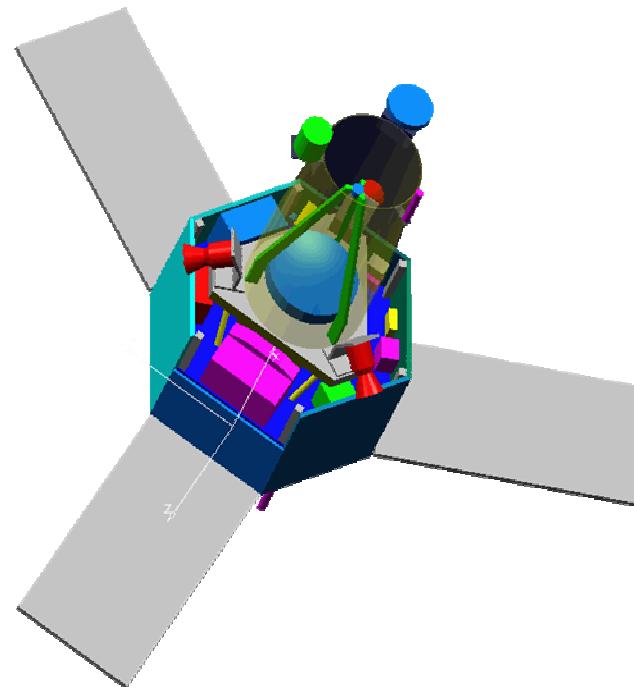


Vancouver, BC
Radarsat-2
Ultrafine mode



Pleiades (F)

- ↗ Owner
 - ↗ CNES
 - ↗ Commercial distribution
 - ↗ (incl. Military use)
- ↗ Constellation
 - ↗ Two active satellites
- ↗ Launch date
 - ↗ mid 2009
- ↗ Prime Instrument
 - ↗ High resolution optical imager
- ↗ Resolution/swath
 - ↗ 0,7 m pan & 4* 2,8 m ms / > 20km



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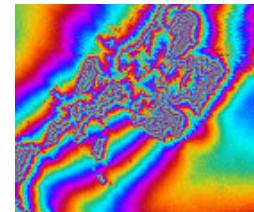
German contribution to the GMES space component

Sentinel 1: SAR Imaging:

SRTM

TerraSAR-X

TanDEM-X



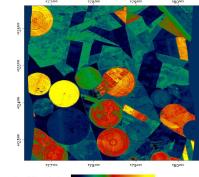
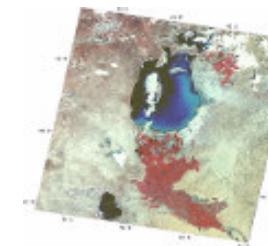
Sentinel 2: Superspectral Imaging:

BIRD

RapidEye

IRS-P6; ResourceSAT

EnMAP



Sentinel 2b: Very High resolution optical mapping:

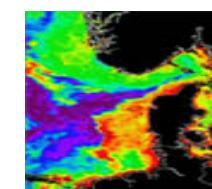
IKONOS, GeoEye-1

CartoSAT-1, CartoSAT-2



Sentinel 3: Ocean Monitoring:

EnMAP



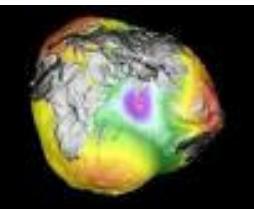
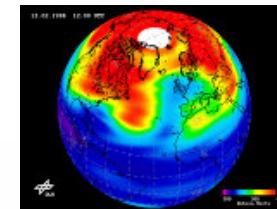
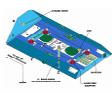
Sentinel 4 & 5 atmospheric monitoring:

GOME

Sciamachy

Earth System understanding:

Grace, Champ



TerraSAR-X – First German SAR Satellite

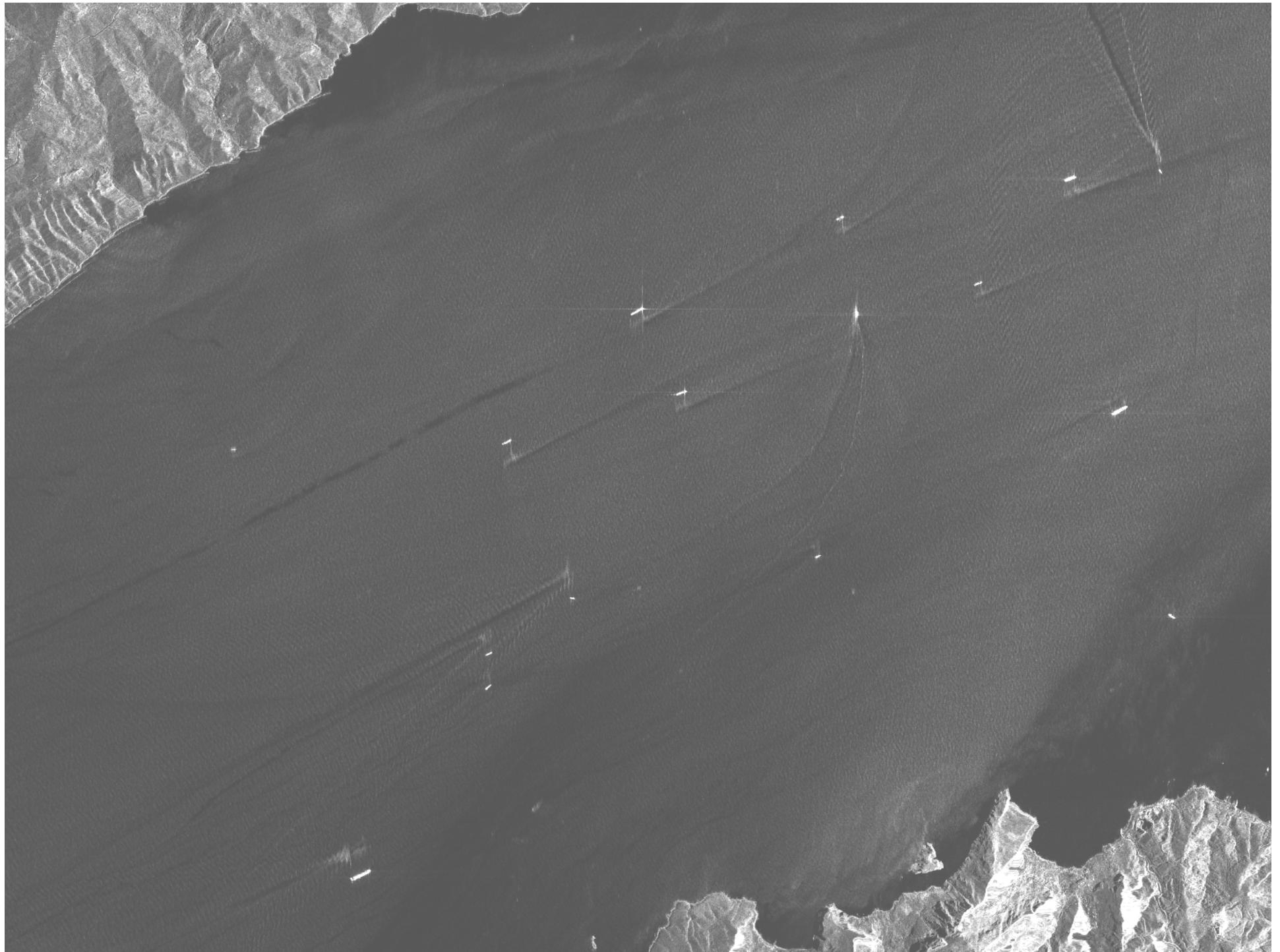
Launch: June 15, 2007

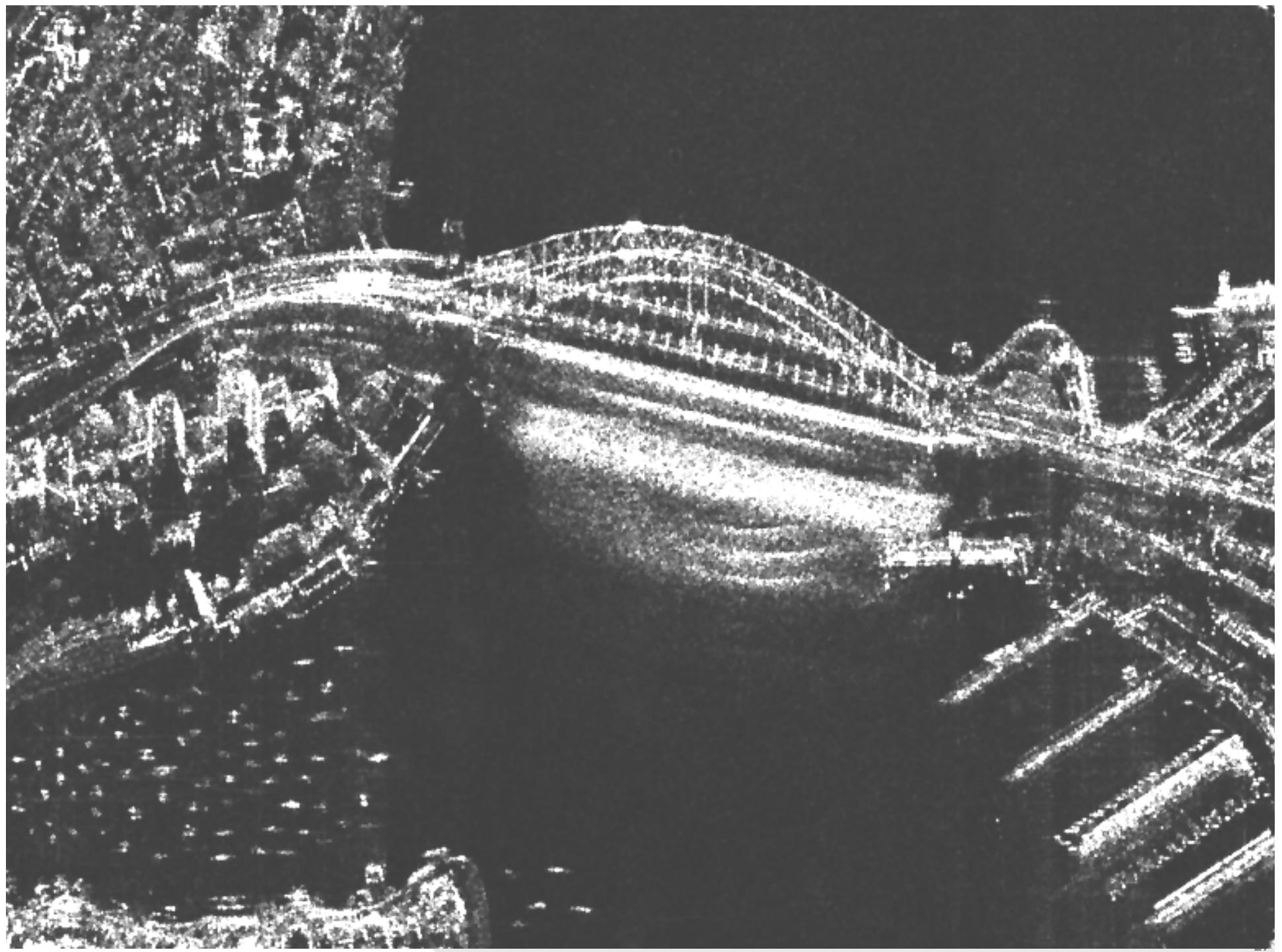
Orbit: 514 km

Spat. Res.: down to 1 m

- Approved formation flight with TanDEM-X (Launch 2009).
- Mission control, data acquisition, processing and distribution from DLR institutes in Oberpfaffenhofen
- Scientific coordination and applications: DLR-DFD
- Commercial distribution: Astrium/InfoTerra
- Contribution to GMES



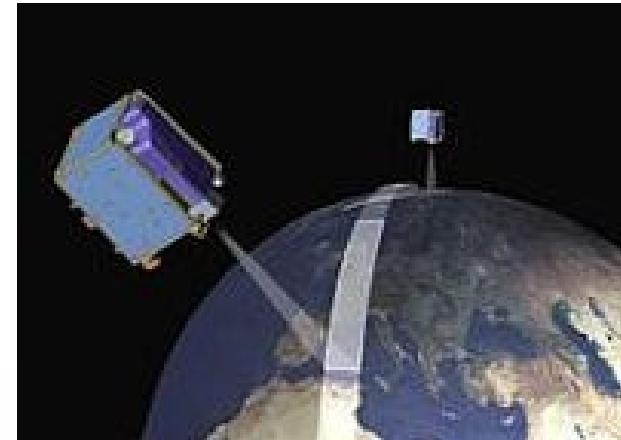
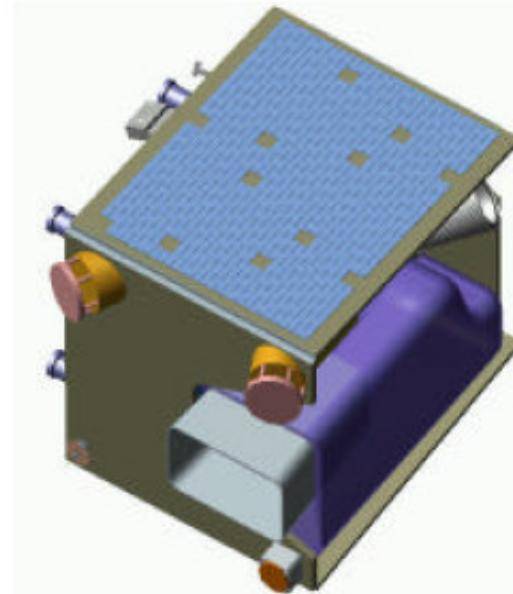






RapidEye (D)

- ↗ Owner
 - ↗ Rapid Eye AG, Germany
 - ↗ Private and public investors
- ↗ Constellation
 - ↗ Five active micro satellites in constellation, 3 planes
- ↗ Launch date
 - ↗ Mid 2008
- ↗ Prime Instrument
 - ↗ Optical, 5 bands
- ↗ Resolution/swath
 - ↗ 6,5 m / 80km



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RapidEye system characteristics

Mission characteristic	Information												
Number of Satellites	5												
Spacecraft Lifetime	7 years												
Orbit Altitude	630 km in Sun-synchronous orbit												
Equator Crossing Time	11:00 am (approximately)												
Sensor Type	Multi-spectral push broom imager												
Spectral Bands	Capable of capturing any of the following spectral bands: <table><thead><tr><th>Name</th><th>Spectral Bands (nm)</th></tr></thead><tbody><tr><td>Blue</td><td>440 – 510</td></tr><tr><td>Green</td><td>520 – 590</td></tr><tr><td>Red</td><td>630 – 685</td></tr><tr><td>Red Edge</td><td>690 – 730</td></tr><tr><td>NIR</td><td>760 – 850</td></tr></tbody></table>	Name	Spectral Bands (nm)	Blue	440 – 510	Green	520 – 590	Red	630 – 685	Red Edge	690 – 730	NIR	760 – 850
Name	Spectral Bands (nm)												
Blue	440 – 510												
Green	520 – 590												
Red	630 – 685												
Red Edge	690 – 730												
NIR	760 – 850												
Ground sampling distance (nadir)	6.5 m												
Pixel size (orthorectified)	5 m												
Swath Width	77 km												
On board data storage	1500 km of image data per orbit												
Revisit time	Daily (off-nadir) / 5.5 days (at nadir)												
Image capture capacity	4 million sq km/day												
Dynamic Range	12 bit												



Environmental Mapping and Analysis Program

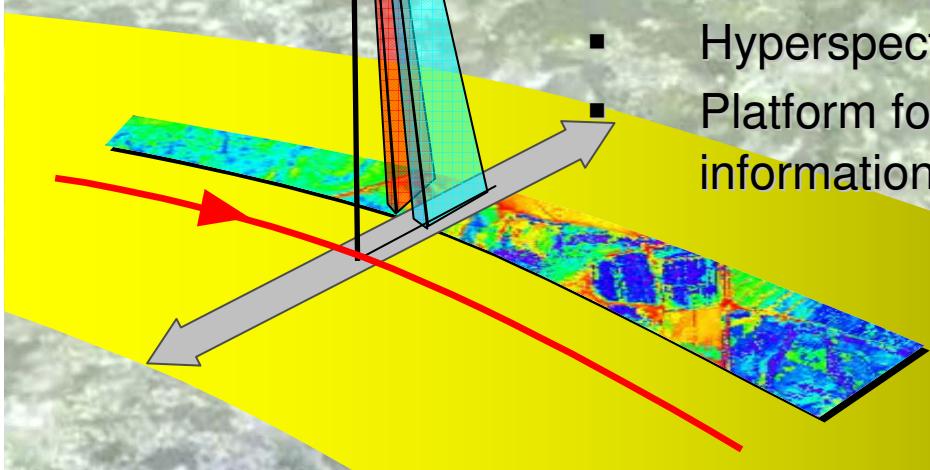


Launch: 2011

Spatial Res.: 30m at 30km swath

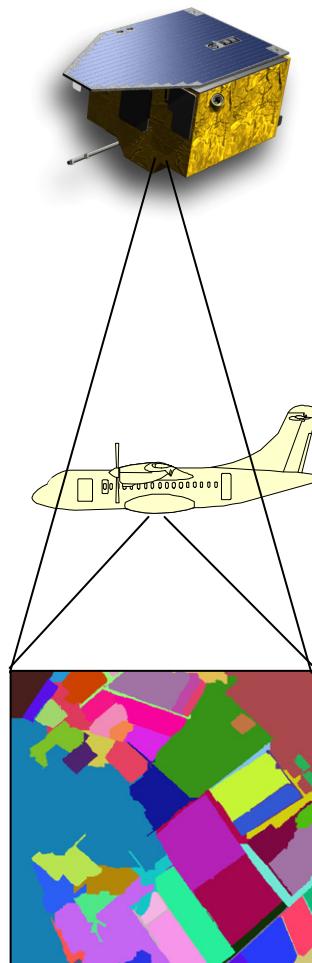
Repetition: 5 days at +/- 30° off-nadir

- DLR Satellite, Principle investigator: GFZ
- Satellite Prime: Kayser-Threde, Munich, Germany
- Hyperspectral instrument, >200 channels (420–2450 nm)
- Platform for further operationalization of methods for information retrieval for land surface monitoring





EnMAP – Principle and Applications

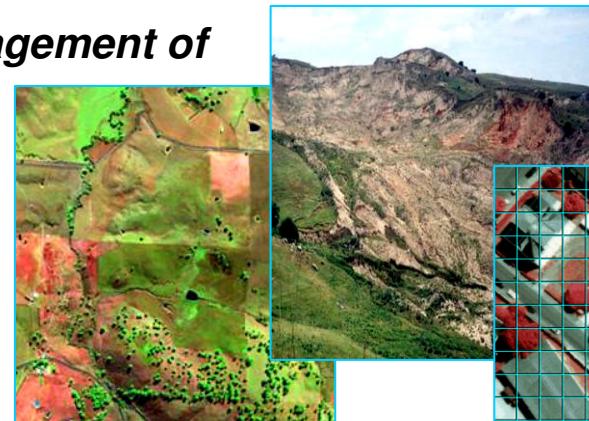


EnMAP

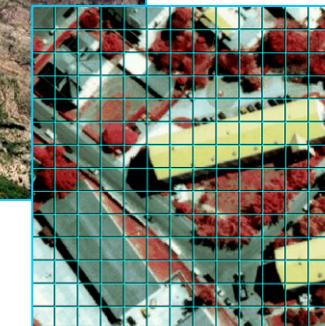
ARES

*parameter
extraction
and
modeling*

*management of
agricultural
and forest
ecosystems*

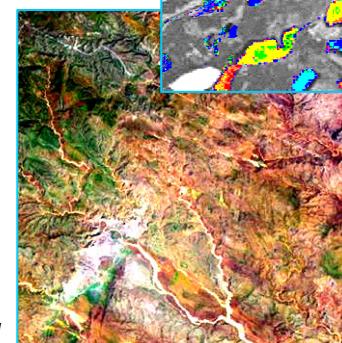


*hazard
assessment*

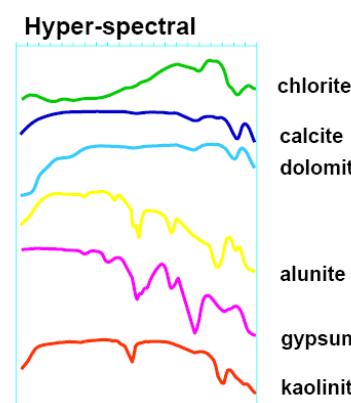
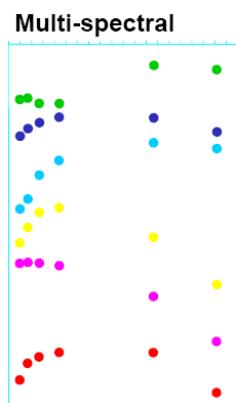


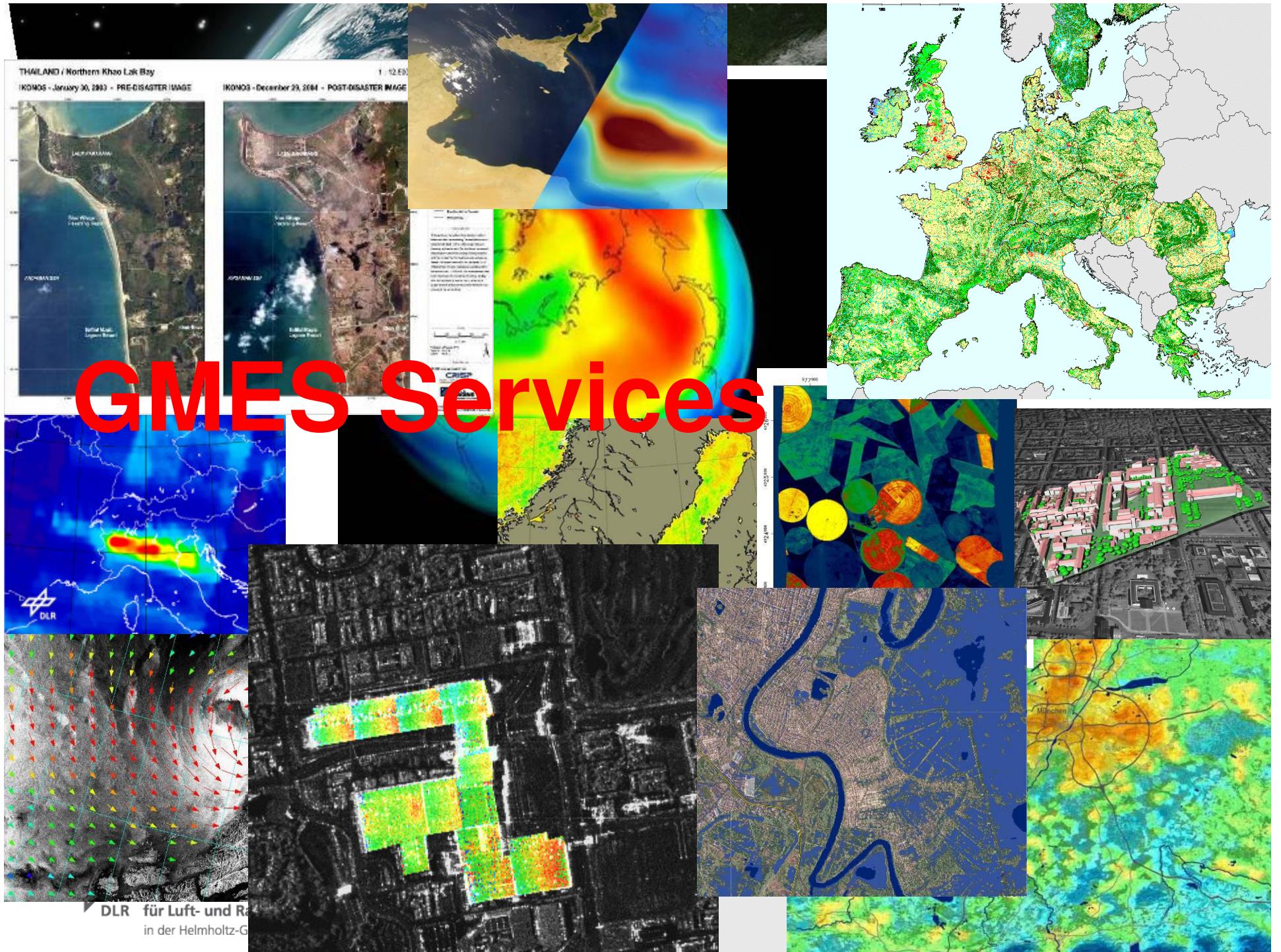
*urban
develop-
ment*

*inland
water*



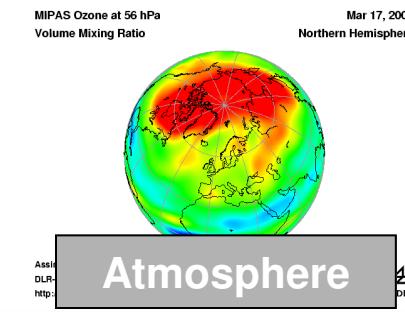
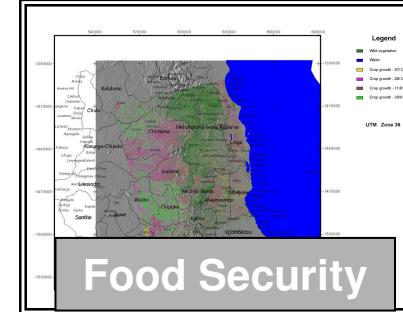
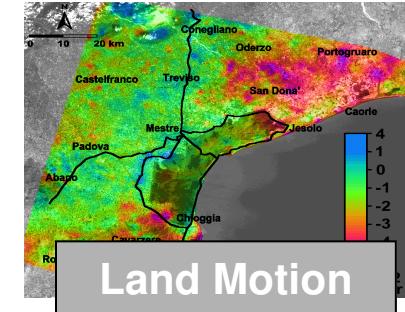
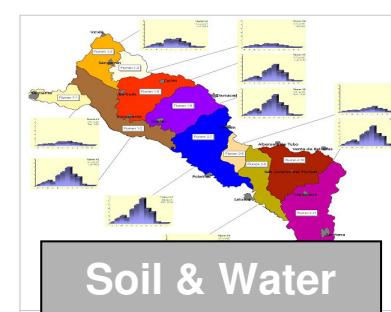
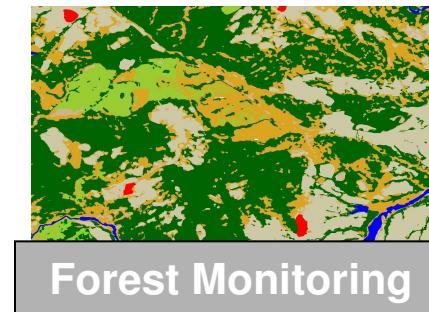
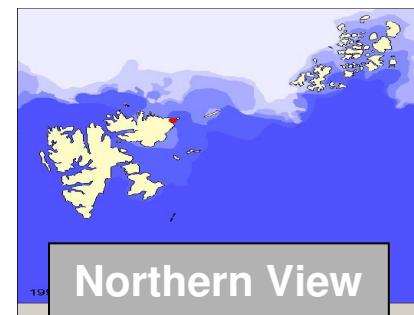
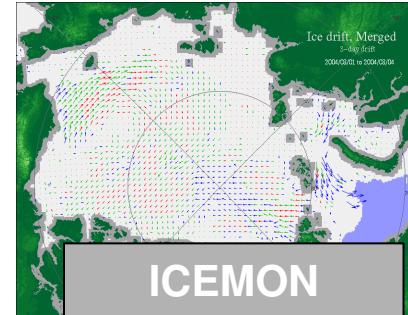
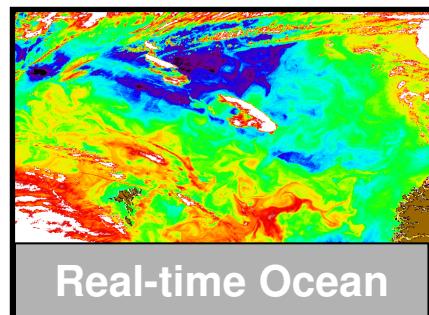
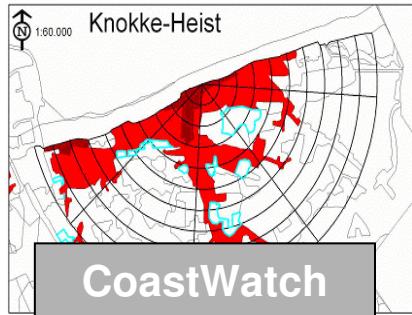
*dry-
land
degradation*







ESA GSE Initial Services in consolidation



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The GMES service element

*Fast
Track
Services*

*Pilot
Services*

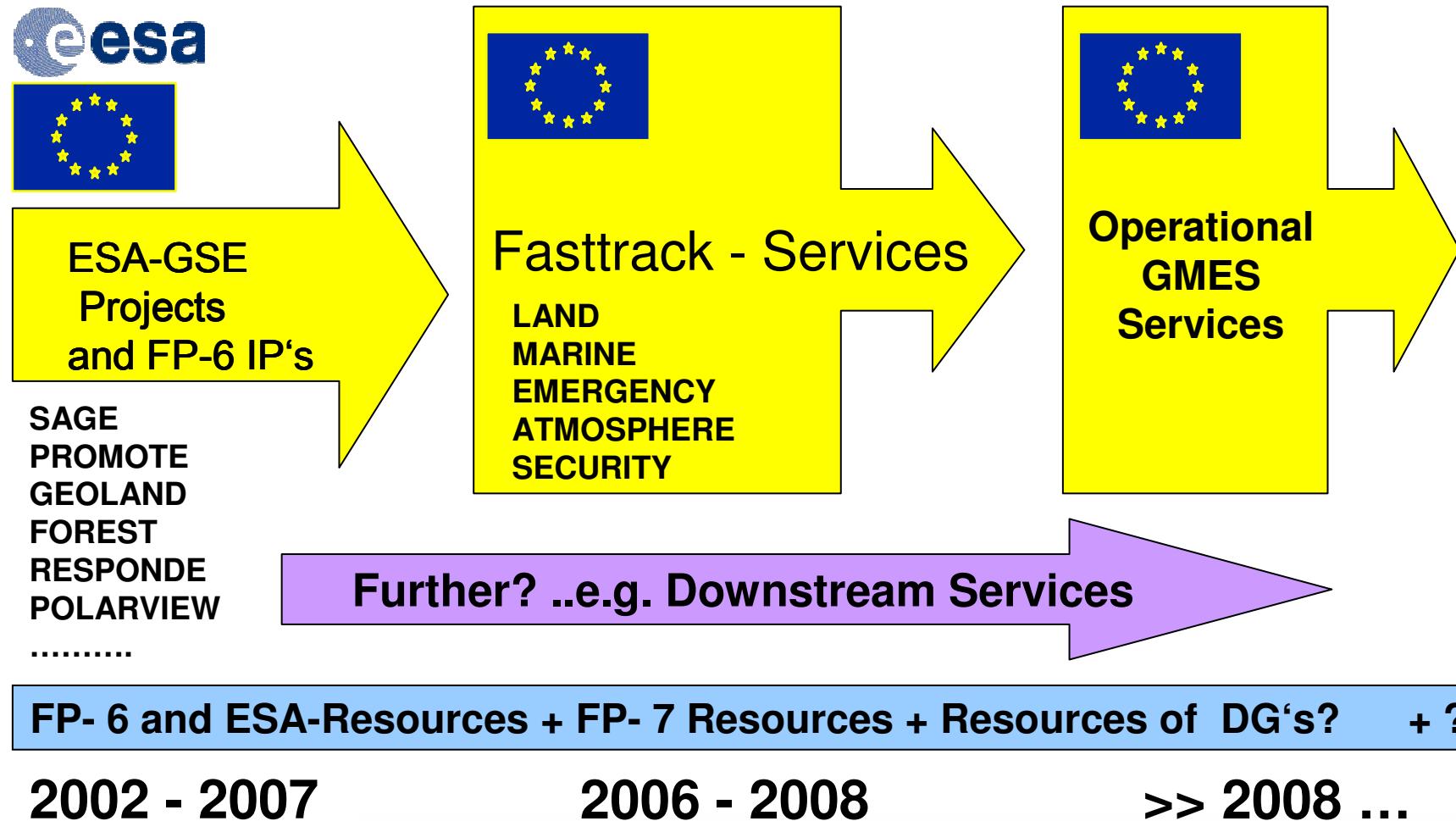


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GMES Services and Evolution Overview





GMES Services implementation

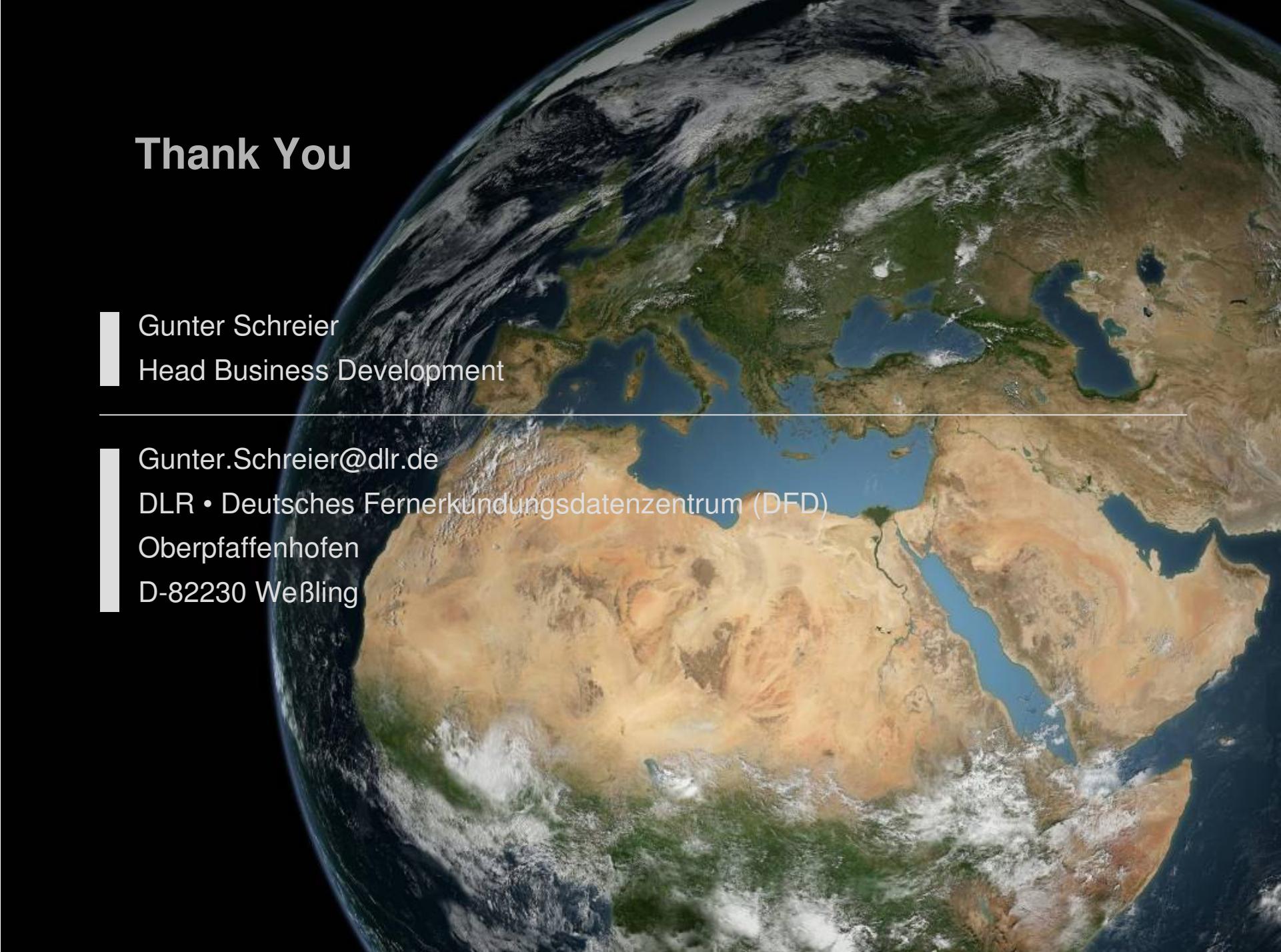


Under implementation
of FP7 (start 2008)

Five Proposals by European Consortia

- GeoLand II
- MyOcean
- SAFER
- MACC
- G-Mosaic

Under implementation
of FP7 (call end 2008)



Thank You

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